

Matrices

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Matrix

MatLab/Octave is based on matrices.
All operations are done on an entire matrix

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

How to multiply it by 2?

PASCAL & C

```
for i := 1 to 3
  for j := 1 to 3
    B[i, j] = 2*A[i, j];

for (i=0; i<3; i++) {
  for (j=0; j<3; j++) {
    B[i,j] = 2*A[i,j];
  }
}
```

Octave

```
B = 2*A
```

Matrix (vector) definitions

Note: A vector is a one-dimensional matrix. An array with one index.

Operations:

$a = [1, 2, 3]$ $(1 \ 2 \ 3)$

separate elements in row (*)

$a = [1, 2, 3; 4, 5, 6; 7, 8, 9]$ or $a = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$

separate rows

$a = [1; 2; 3]$ or $a = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$

separate rows

*: Note: comma ',' can also be omitted – $[1 \ 2 \ 3]$ is equal to $[1, 2, 3]$ – but for readability it is better to keep it (in other languages like Mathematica, a space means multiplication)

Scalar - Vector - Matrix - Tensor - Array

All are tensors (when dealing with numbers):

scalar: zeroth order tensor. single value, no index

vector: first order tensor. 1 index per element

matrix: second order tensor. 2 indexes per element

tensor: nth order. n indexes per element

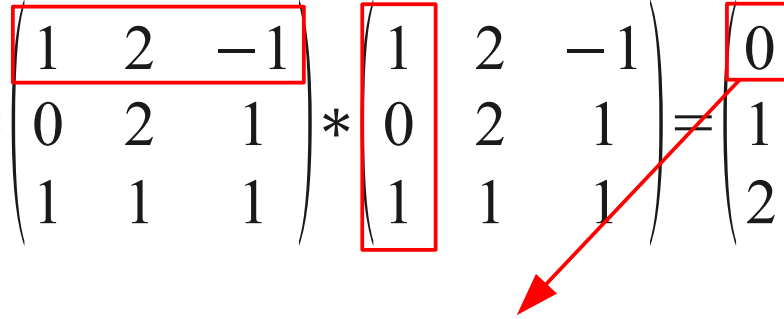
In **programming**: all tensors except scalars are called arrays

In **MatLab**: all (including scalar!) are called array / matrix

Matrix multiplication, matrix vs. array

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

How to take the square?
 $B = A * A, B = A^2$

$$B = A^2 = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix}^2 = A * A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} * \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 5 & 0 \\ 1 & 5 & 3 \\ 2 & 5 & 1 \end{pmatrix}$$


$1 \times 1 + 2 \times 0 - 1 \times 1 = 0$, etc.

$$B = A^2 = \begin{pmatrix} 1^2 & 2^2 & (-1)^2 \\ 0^2 & 2^2 & 1^2 \\ 1^2 & 1^2 & 1^2 \end{pmatrix} = \begin{pmatrix} 1 & 4 & 1 \\ 0 & 4 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

?

The crucial point

$$A = \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$

How to take the square?
 $B = A * A$, $B = A^2$

$$\begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} * \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 5 & 0 \\ 1 & 5 & 3 \\ 2 & 5 & 1 \end{pmatrix}$$

Octave (matrix)

$B = A * A$ $B = A^2$

$$\begin{pmatrix} 1^2 & 2^2 & (-1)^2 \\ 0^2 & 2^2 & 1^2 \\ 1^2 & 1^2 & 1^2 \end{pmatrix} = \begin{pmatrix} 1 & 4 & 1 \\ 0 & 4 & 1 \\ 1 & 1 & 1 \end{pmatrix}$$



Octave (array)

$B = A .* A$ $B = A.^2$

Matrix and array multiplication

$$\begin{matrix} & \xleftrightarrow{n} \\ \begin{matrix} \uparrow m \\ \downarrow m \end{matrix} \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} & * & \begin{matrix} \xleftrightarrow{k} \\ \begin{matrix} \uparrow n \\ \downarrow n \end{matrix} \end{pmatrix} \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} & = & \begin{matrix} \xleftrightarrow{k} \\ \begin{matrix} \uparrow n \\ \downarrow n \end{matrix} \end{pmatrix} \begin{pmatrix} -2 & 3 & 0 \\ -1 & 1 & 1 \\ 1 & 0 & 2 \end{pmatrix} \begin{matrix} \downarrow m \end{matrix} \end{matrix}$$

Octave (matrix)

$$C = A * B$$

Width of A has to be equal to **height of B**
C will have width k and height m

$$\begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} .* \begin{pmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 1 & -1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -1 \\ 0 & 2 & 0 \\ 1 & -1 & 1 \end{pmatrix}$$

Octave (array)

$$C = A .* B$$

Matrices have to be of same size in **all** dimensions

The crucial point

Multiplying with scalars: the '.' makes no difference!

(Not very consistent, isn't it?)

With scalars the '.' is always there

$$2 * \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 4 & -2 \\ 0 & 4 & 2 \\ 2 & 2 & 2 \end{pmatrix}$$

$$2 .* \begin{pmatrix} 1 & 2 & -1 \\ 0 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} = \begin{pmatrix} 2 & 4 & -2 \\ 0 & 4 & 2 \\ 2 & 2 & 2 \end{pmatrix}$$

Octave (matrix)

```
B = a * A
```



Octave (array)

```
B = a .* A
```

Functions on matrices

Using functions: always element by element

$$\sin \begin{pmatrix} -\pi/2 & 0 & \pi/2 \\ 0 & \pi/2 & \pi \\ 0 & -2\pi & \pi/2 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Octave

```
B = sin(A)
```

$$\begin{pmatrix} -2 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & -2 & 2 \end{pmatrix} < 1 = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 0 \\ 1 & 1 & 0 \end{pmatrix}$$

Octave

```
B = A < 1
```

*: '1' means 'true'

Ranges

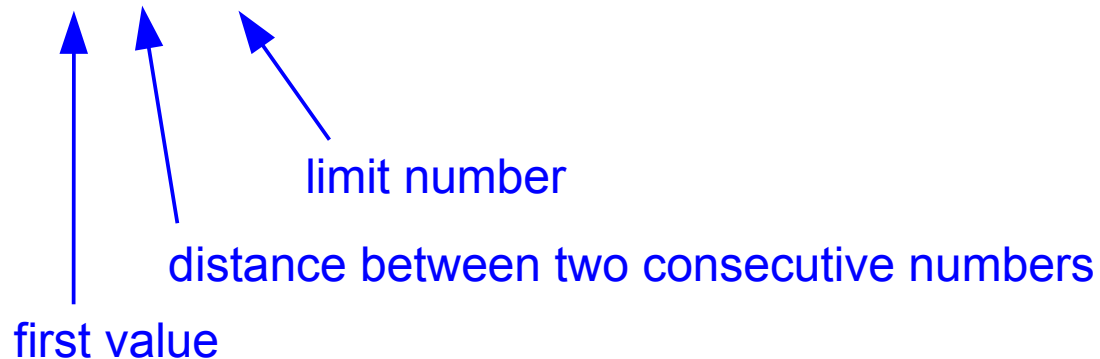
Ranges can be rapidly defined using the colon, ':'

```
a = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10]
```

```
a = 1:10
```

```
a = [1, 3, 5, 7, 9]
```

```
a = 1:2:10
```



Access to the values

An element of a matrix can be accessed by its indexes

For example (2 dimensional array a):

`a(row, column)`

```
Octave:1> a = [1, 2, 3, 4, 5, 6, 7, 8, 9, 10];
```

```
Octave:2> a(3)
```

```
ans = 3
```

```
Octave:3> a(1,6)
```

```
ans = 6
```

```
Octave:1> a = [1; 2; 3; 4; 5; 6; 7; 8; 9; 10];
```

```
Octave:2> a(4)
```

```
ans = 4
```

```
Octave:3> a(7,1)
```

```
ans = 7
```

A vector is considered (also) a matrix with 1 line or 1 column
(Not very consistent, isn't it?)

Access to the values

An entire column or row

`a(:, column)`

`a(row, :)`

```
Octave:1> a = [1, 2, 3;  
               4, 5, 6;  
               7, 8, 9];
```

```
Octave:2> a(2, :)
```

```
ans =
```

```
4 5 6
```

```
Octave:3> a(:, 1)
```

```
ans =
```

```
1
```

```
4
```

```
7
```

Interesting

end gives last column/row index. Ex.: `a(end, end)` yields 9

eye (*n*) : unity matrix $n \times n$

zeros (*m*, *n*) : matrix $m \times n$ filled with zeros

ones (*m*, *n*) : matrix $m \times n$ filled with ones

rand (*m*, *n*) : matrix $m \times n$ filled with random values 0..1

linspace (*start*, *stop*, *number*) : vector with **number** equally spaced elements from **start** to **stop**
(equal to `start:(stop-start)/(number-1):stop`)

inv (**A**) : inverse matrix

A' : transposed matrix

Interesting

max: largest element of vector. $\max(\max(A))$ is maximum of array
min: smallest element of vector. $\min(\min(A))$ is minimum of array
mean: average of elements of vector
std: standard deviation of elements of vector
sort: sorts vector small $\rightarrow$ big
sum: sum of elements of vector
prod: product of elements of vector
diff: difference between consecutive elements