

Electronic Complements Exam  
9/01/2014

①

See lecture notes p. 12

$$v_1 = - \frac{V_X R_{33}}{2r_e} \quad , \quad v_2 = + \frac{V_X R_{34}}{2r_e}$$

fed into dif. amp.  $100 \times$

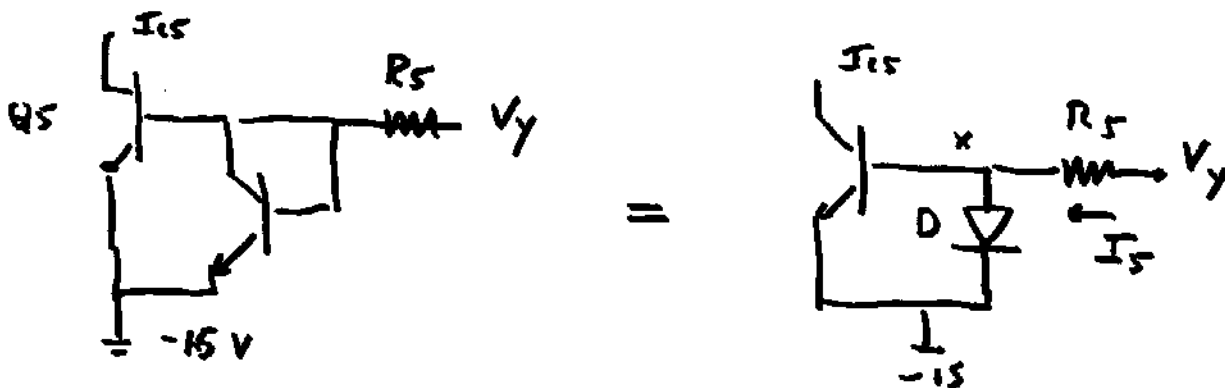
$$V_o = 100 \times \frac{R_{34} + R_{33}}{2r_e} V_X$$

$r_e$  is (polarization current of transistors)

$$\frac{V_T}{I_E}$$

$$I_E = \frac{1}{2} I_{CS}$$

How much is  $I_{CS}$  ?!



At x  $V = -15V + 0.7$

$$I_s = \frac{V_y - (0.7V - 15V)}{R_5}$$

$\beta = \infty \Rightarrow I_s$  goes through D.

$I_{CS}$  is copying this (current mirror)

$$I_{CS} = \frac{V_y + 15V - 0.7V}{R_5}$$

(2)

The circuit does not work very nice linear, but  $V_x$  on  $V_y$  both modulate  $V_o$

$$V_o = 100 \cdot \frac{R_{34} + R_{33}}{2 R_5} \cdot \frac{V_x \cdot (V_y + 15 - 0.7)}{V_T}$$

a) It is a two-quadrant amplifier

$V_x$  can be positive and negative (like in any dif. pair. amp.)

$V_y$  can have only current going down in current source, thus  $V_y + 15 - 0.7 > 0$

2] A1 is an amplifier with the gain depending on the value of the resistance of T1  
Simplified: voltage divider  $R_2 : R_1 \approx \frac{1}{100}$  at entrance. Then if  $R_{T1} = \infty$  a 10 times amp ( $R_2/R_3$ )  
If T1 conducting  $R_3$  reduces to  $5V/20mA$   
 $= 250 \Omega$  (derivative of Fig.) · A1 gain = 60.

IC2 is a final amplifier of  $10 \times$ . Thus, the overall gain varies between  $\frac{1}{100} \times 10 \times 10 = 1$  to  $\frac{1}{100} \times 60 \times 10 = 6$ .

A2 takes care of the feedback. HPF at entrance ( $C_4, R_9$ ). Gain equal to P1 potencioneter, between 0 and 1



(3)

The exit of A2 can discharge C1 through D1

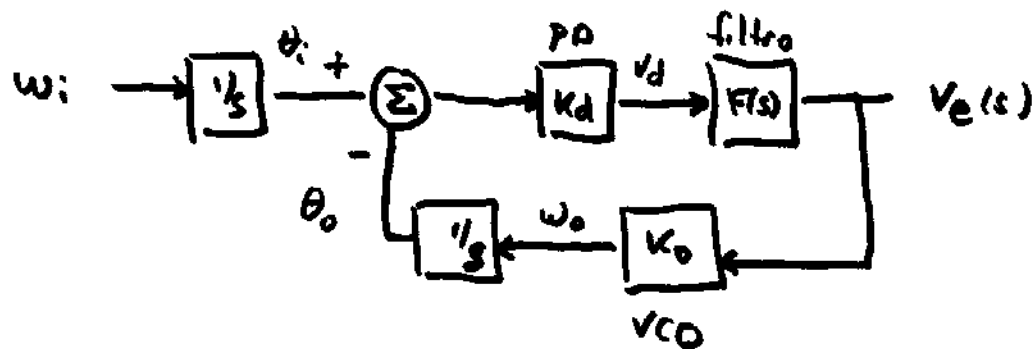
$R_7, R_8$  and  $C_1$  form a 'filter' (LPF), charging

$C_1$  through  $R_7$  ( $\tau = 10^6 \Omega \times 10 \mu F = 10s$ ) and

discharging basically through  $R_8$  ( $\tau = 1500 \Omega \times 10 \mu F = 15ms$ ).

This changes voltage at gate of T1 and regulating gain of A1.

3] a) See lecture notes



$$\theta_o = (\theta_i(s) - \theta_o(s)) k_d F(s) k_o \cdot \frac{1}{s} \Rightarrow$$

$$H(s) \equiv \frac{\theta_o(s)}{\theta_i(s)} = \frac{k_v F(s)}{s + k_v F(s)} \quad \text{with } k_v = k_d k_o$$

b) without LPF

$$H(s) = \frac{k_v}{k_v + s} = \frac{1}{1 + s/k_v} \quad (s = j\omega)$$

is like LPF  $\frac{1}{1 + j\omega/\omega_c}$  with cut-off frequency

$$\omega_c = k_v = k_d k_o = 1V \cdot \frac{4\pi \text{ krad/s}}{V}$$

(4)

$$\omega_c = 4000\pi \text{ rad/s} \quad , \quad f_c = 2000 \text{ Hz}$$

c) At 110 kHz, at lock  $\omega_o = \omega_i = 2\pi \cdot 110 \text{ kHz}$   
 $f_o = 100 \text{ kHz} + V_e \cdot 2 \text{ kHz/V} = 110 \text{ kHz} \Rightarrow$

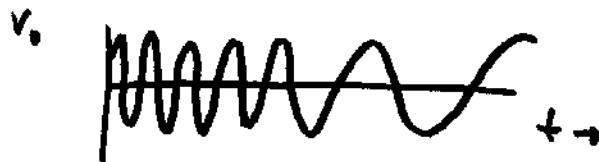
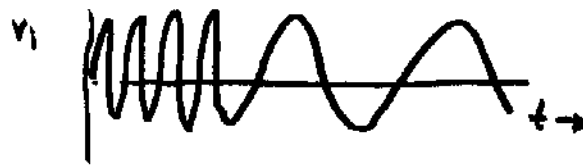
$$V_e = 5 \text{ volt.}$$

At 100 kHz, at lock  $\omega_o = \omega_i = 2\pi \cdot 100 \text{ kHz}$

$$f_o = 100 \text{ kHz} + V_e \cdot 2 \text{ kHz/V} = 100 \text{ kHz} \Rightarrow$$

$$V_e = 0 \text{ volt}$$

The relaxation time going from 5 volt to 0 is given by  $K_v$ ,  $\tau = \frac{1}{\omega_c} = \frac{1}{4_v} = \frac{1}{4000\pi} \text{ s}$



$\tau$  exaggerated

d) From electronics II we know about stability  
 The transfer function was (negative feedback, '+' sign!)

$$\frac{v_o}{v_i} = \frac{A}{1 + AB}$$

and we analyzed  $AB$ . If it hit Barkhausen

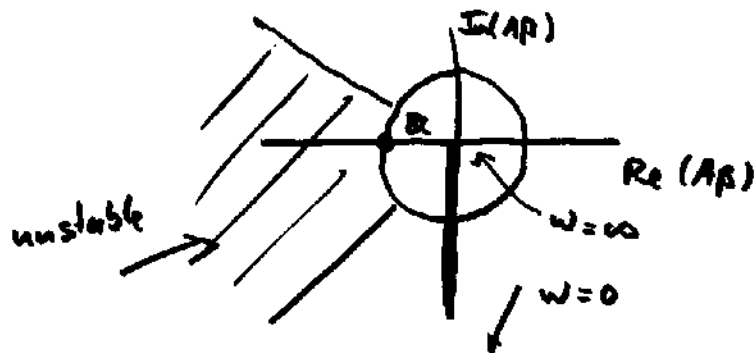
(5)

Criterion it was not stable

$A\beta$  in our case is

$$A\beta = k_d F(s) k_o \cdot \frac{1}{s}$$

without filter ( $F(s)=1$ ),  $A\beta = k_d k_o / s = -j k_d k_o / \omega$



stable!

with filter

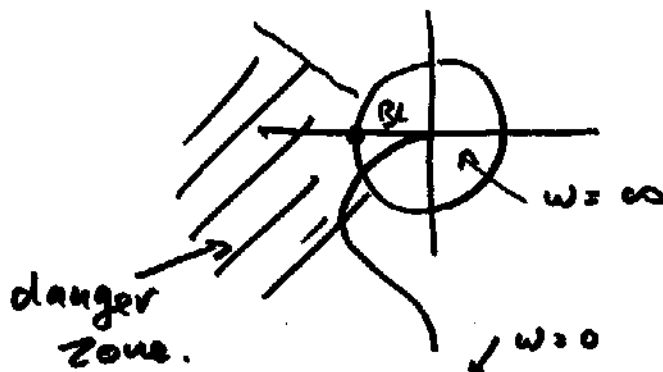
$$A\beta = \frac{k_v}{s(1 + s/\omega_c)}$$

$$\omega_c = \frac{1}{RC} = \frac{1}{\tau}$$

$$= \frac{k_v}{j\omega + (j\omega)^2/\omega_c} = \frac{k_v}{j\omega - \omega^2/\omega_c}$$

$$\omega = \infty : A\beta = -0 \quad \phi = 180^\circ$$

$$\omega = 0 : A\beta = -j0 \quad \phi = -90^\circ$$



can be unstable!

4] See lecture notes.